



# NGBe

Permanent magnet  
brushless servomotors

IT/EN



### A dynamic, strong and ambitious Group

Orange1 Holding is an international renown Group, one of the most important European manufacturers of single-phase and three-phase asynchronous electric motors. It has an annual capacity of more than 1 million motors and 5 million electric stators with an annual turnover of approx 235 million euro and more than 1600 workers in 15 production facilities. The group, established in 1971 by Leone Donazzan, chaired today by his son Armando Donazzan, is strongly focused on technological innovation, performance and customization to meet individual clients requirements.

### Un gruppo forte, dinamico e ambizioso

Orange1 Holding è un gruppo internazionale, uno dei più importanti produttori europei di motori elettrici monofase e trifase. Ha una capacità produttiva annuale di oltre 1 milione di motori e 5 milioni di statori elettrici con un fatturato annuo di circa 235 milioni e più di 1600 lavoratori in 15 sedi. Il gruppo fondato nel 1971 da Leone Donazzan, presieduto oggi dal figlio Armando Donazzan, è fortemente focalizzato sull'innovazione tecnologica e sulla customizzazione di prodotto per soddisfare le esigenze di ogni cliente.



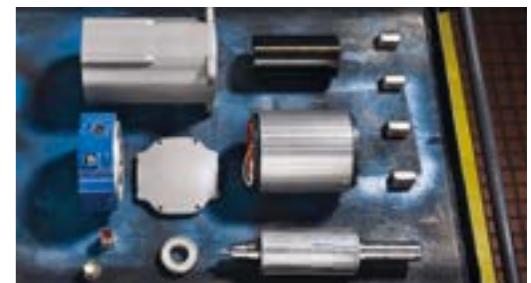
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Nominal torque Nm  
Nominal power kW



4,9 Nm  
1,9 kW



11,9 Nm  
2,7 kW



30 Nm  
4,1 kW

NGBe143.TEBC 39 Nm  
9,1 kW

NGBe200 86 Nm  
27,0 kW

NGBe200.TEBC 116 Nm  
36,4 kW

## LINEA NGBe NGBe SERIE



**SERVOMOTORI BRUSHLESS NGBe** — Pensati per le esigenze sempre più estreme dell'automazione industriale che richiedono sistemi ad elevate prestazioni, miglior affidabilità e ridotta manutenzione.

La serie NGBe è stata sviluppata utilizzando materiali di altissima qualità, nuovi dettagli estetici e funzionali sono stati introdotti per ottenere ingombri ridotti e una riduzione dei costi per il cliente.

**THE NGBe BRUSHLESS RANGE** — The NGBe brushless servomotors are designed to meet the increasingly demanding needs of the automation industry, which require high-performance systems, greater reliability, and reduced maintenance. We used high-quality materials to develop the NGBe series. The new aesthetic and functional details introduced allowed us to reduce the overall dimensions, resulting in great savings for the customer.

## Caratteristiche principali — Main features

### Affidabilità — Reliability

#### Magneti

Realizzati in terre rare NeFeB, rivestiti superficialmente per garantire elevate prestazioni e una protezione totale del magnete da fenomeni di ossidazione e corrosione vengono inoltre contenuti da un elemento tubolare.

#### Colle epossidiche

Dedicate all'incollaggio dei magneti al rotore per consentire un bloccaggio strutturale degli stessi, il riempimento dei giochi ed un'ottima protezione del magnete.

#### Cuscinetti

Di tipo a sfere con schermi, prelubrificati a vita. Il cuscinetto lato accoppiamento è stato scelto con un'adeguata capacità di carico radiale e sul lato opposto un cuscinetto speciale con grasso per alte temperature.



#### Magnets

*Magnets are made of NeFeB rare earth and are surface-coated to guarantee high performance and protect them against oxidation and corrosion.*

*Moreover, they are contained in a tubular element.*

#### Epoxy glues

*Used to glue the magnets to the rotor and lock them in place, fill in gaps, and protect the magnet.*

**Stator — The motors manufactured with the stator's monolithic structure, thus guaranteeing reliability and greater structural rigidity.**

### Modularità — Modularity

**NGBe** è progettato prevedendo un'uguale predisposizione meccanica per il montaggio di **4 differenti tipi di feedback motore**.

Il fissaggio del motore alle vostre macchine è agevole grazie all'**accesso diretto delle viti di fissaggio della flangia** B5, V1 o V3.

Le connessioni previste per i connettori M23 hanno la funzionalità di **aggancio rapido**, garantendo praticità anche nelle situazioni di impianti con difficile accessibilità.

**NGBe** has an equal mechanical set-up for assembling **4 types of motor feedback**.

The motor can be easily fastened to your machines thanks to the **direct access to the B5, V1 or V3 flange fastening screws**.

The connections of the M23 connectors have the **quick coupling function**, which guarantees practicality, even when systems are difficult to access.

### Isolamento — Insulation

Tutta la **serie NGBe** è in **classe termica F**, pertanto la massima sovratemperatura dell'avvolgimento ammessa è di 105K (temperatura max ambiente 40°C).

L'avvolgimento dello statore è progettato con un **doppio isolamento elettrico**. Una prima impregnazione di vernice isolante seguita da un secondo riempimento con resina epossidica, in ambiente sottovuoto. Queste attenzioni garantiscono un eccellente grado di affidabilità dell'avvolgimento. Un'ottima soluzione per la protezione dello statore anche nei momenti di smontaggio per le operazioni di manutenzione.

The entire **NGBe series** has a **class F thermal rating**; therefore, the maximum winding over-temperature permitted is of 105K (maximum room temperature: 40°C).

The winding of the stator is designed with **double electrical insulation**. It is first impregnated with an insulating paint and then it is filled with an epoxy resin in a vacuum environment. These details make the winding extremely reliable. An excellent solution to protect the stator during disassembly operations for maintenance purposes.

**References standard — Our brushless servomotors comply with the IEC 60034 standard concerning rotating electrical machines. Therefore, they comply with the regulations of most of the EU Countries.**



## Soluzioni costruttive — Constructive solutions

### Dummy slot

Sono previste delle nicchie sullo stator per produrre effetti sulla coppia simili a quelli dovuti alle cave, compensandoli. *The slots on the stator produce effects on the torque similar to those on the hollows, thereby compensating them.*



### Magnet phase shift

Nello stesso modulo di rotore i magneti sono collocati in posizione asimmetrica. *The magnets are placed in an asymmetric position in the same rotor module.*

### Stepped skewing

Posizione disallineata dei moduli del rotore Misaligned position of the rotor modules.



"I servomotori **NGBe** sono progettati per ottenere una ridotta pendolazione di coppia, a favore di un'ottima rotondità di moto."

"**NGBe** servomotors are designed to reduce torque oscillation and promote excellent rotation regularity."



**NGB evolution**

I NUOVI SERVOMOTORI

**BRUSHLESS —**

L'estetica del prodotto è il risultato di una grande attenzione al rapporto tra forma e funzionalità dei diversi componenti, soluzione capace di offrire un motore dalla forte riconoscibilità e con importanti dettagli funzionali.

**THE NEW BRUSHLESS MOTORS —**

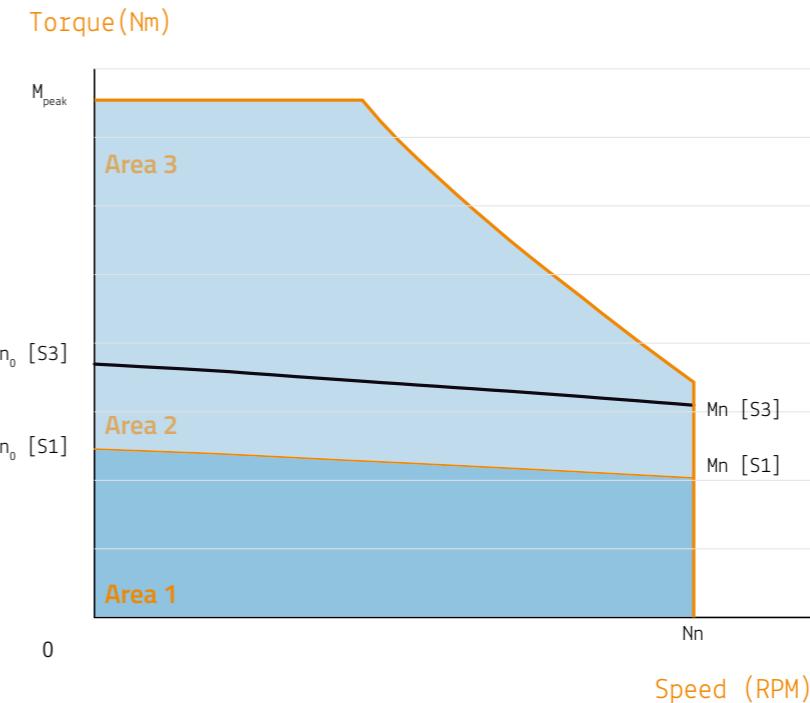
**MOTORS —**

The aesthetics of the product is the result of our great attention to the relationship between the shape and functionality of different components to provide a highly recognizable motor with important functional details.

“L'attenzione che poniamo nella scelta dei materiali, ci consente di proporre servomotori dalle ottime performance, elevata robustezza e massima affidabilità.”

*“Our attention in choosing the materials allows us to provide high-performance, solid, and reliable servomotors.”*

## Definizione dei parametri — Parameters definition



Reference graph for the parameters defined in this catalogue.  
For technical details not included in this document, refer to the NGBe series technical manual.

**■ Area 1:**  
Area di funzione del motore in servizio continuativo S1 (CEI EN 60034-1); la curva  $M_{n_0} - Mn$  indica il declassamento della coppia continuativa erogabile in funzione della velocità.

**■ Area 2:**  
Area di funzione del motore con servizio intermittente periodico S3-40% su periodo di un minuto (CEI EN 60034-1), con 40 secondi a carico costante e 60 secondi con motore a riposo; la curva  $M_{n_0}[S3] - Mn[S3]$  indica il declassamento della coppia quadratica media del ciclo erogabile, in funzione della velocità.

**■ Area 3:**  
Area che descrive la coppia massima fornibile dal motore in relazione alle caratteristiche costruttive dello stesso [ $M_{peak}$ ] e in relazione alla massima tensione fornibile dal convertitore. Nella scelta del motore e avvolgimento si deve considerare la velocità fino a cui viene richiesta l'erogazione della coppia massima.

**■ Area 1:**  
Function area of the motor in continuous running duty S1 (IEC EN 60034-1); the  $M_{n_0} - Mn$  curve indicates the de-rating of the continuous torque supplied according to speed.

**■ Area 2:**  
Function area of the motor with periodic intermittent duty S3-40% over a period of one minute (IEC EN 60034-1), with 40 seconds at constant load and 60 seconds with motor in standby; the  $M_{n_0}[S3] - Mn[S3]$  curve indicates the de-rating of the cycle average square torque supplied, according to speed.

**■ Area 3:**  
This area describes the maximum torque supplied by the motor in relation to its construction features [ $M_{peak}$ ] and maximum converter-supplied voltage. When choosing the motor and winding, it is important to consider the speed up to which the maximum torque has to be supplied.

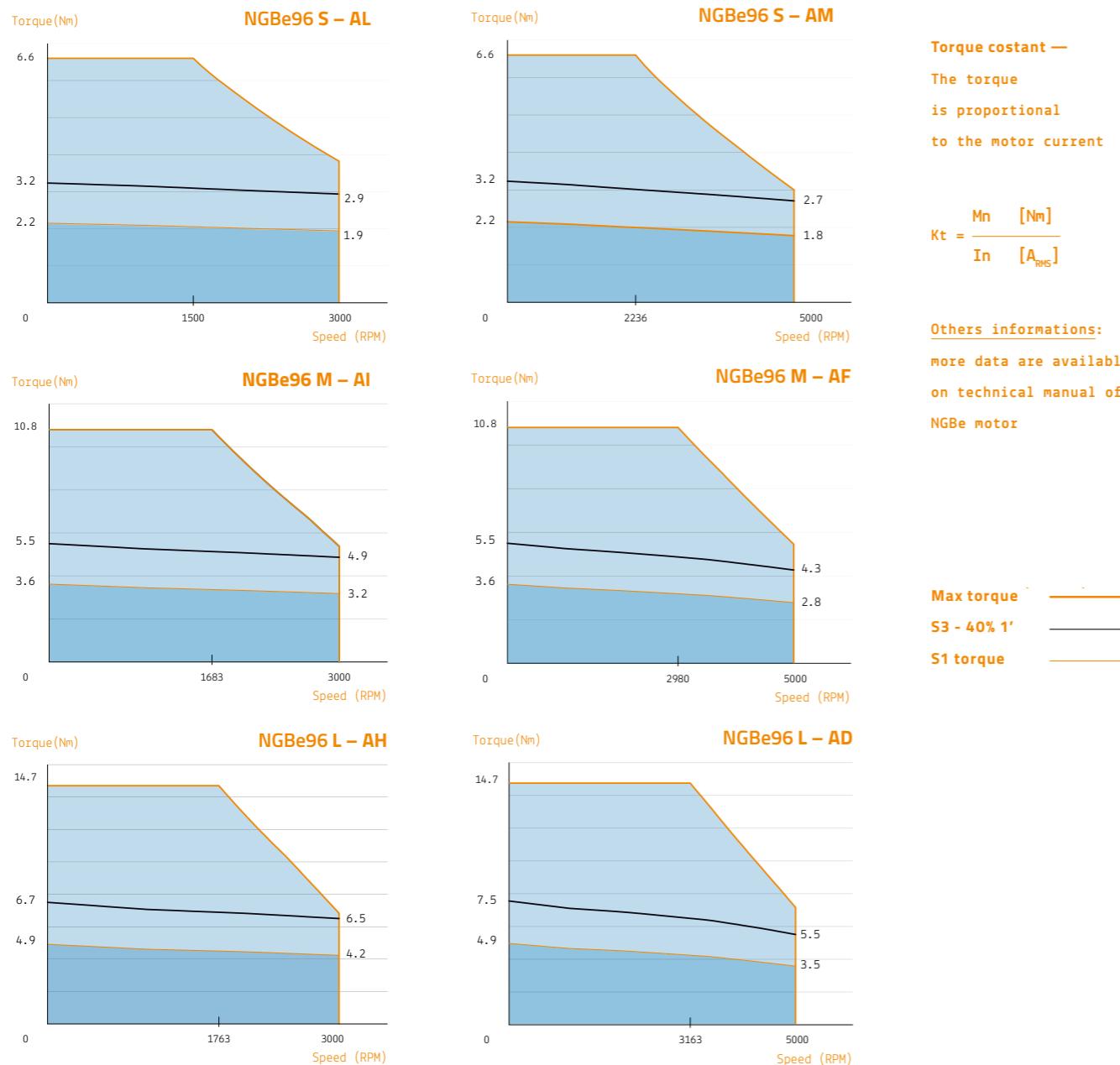
**Nominal Speed  $N_n$ :** It is the maximum speed available at which the maximum overload torque is higher than  $M_{n_0}[S1]$

## NGBe96 TENV - 8 poles - 3x360VRMS motor power supply

	code	Nominal speed Nn	Duty cycle S1			Duty cycle S3-40%, 1 min			Peak torque M <sub>peak</sub>	Torque costant K <sub>t</sub>	Inertia J	Weight m
			Stall torque M <sub>n0</sub>	Nominal torque M <sub>n</sub>	Stall current I <sub>n0</sub>	Stall torque M <sub>n0</sub> [S3]	Nominal torque M <sub>n</sub> [S3]					
NGBe96S	AL	3000 Rpm	2.2 Nm	1.9 Nm	2.2 A <sub>RMS</sub>	3.2 Nm	2.9 Nm	6.6 Nm	0.99 Nm/A <sub>RMS</sub>	1.3 kgcm <sup>2</sup>	3.6 kg	
NGBe96M	AI	3000 Rpm	3.6 Nm	3.2 Nm	2.8 A <sub>RMS</sub>	5.5 Nm	4.9 Nm	10.8 Nm	1.30 Nm/A <sub>RMS</sub>	2.3 kgcm <sup>2</sup>	4.8 kg	
NGBe96L	AH	3000 Rpm	4.9 Nm	4.2 Nm	3.7 A <sub>RMS</sub>	7.5 Nm	6.5 Nm	14.7 Nm	1.34 Nm/A <sub>RMS</sub>	3.4 kgcm <sup>2</sup>	5.4 kg	
NGBe96S	AM	5000 Rpm	2.2 Nm	1.8 Nm	3 A <sub>RMS</sub>	3.2 Nm	2.7 Nm	6.6 Nm	0.71 Nm/A <sub>RMS</sub>	1.3 kgcm <sup>2</sup>	3.6 kg	
NGBe96M	AF	5000 Rpm	3.6 Nm	2.8 Nm	4.6 A <sub>RMS</sub>	5.5 Nm	4.3 Nm	10.8 Nm	0.79 Nm/A <sub>RMS</sub>	2.3 kgcm <sup>2</sup>	4.8 kg	
NGBe96L	AD	5000 Rpm	4.9 Nm	3.5 Nm	5.9 A <sub>RMS</sub>	7.5 Nm	5.5 Nm	14.7 Nm	0.83 Nm/A <sub>RMS</sub>	3.4 kgcm <sup>2</sup>	5.4 kg	



NGBe96 S — B: 152mm  
L: 182mm  
LB: 232mm  
NGBe96 M — B: 179mm  
L: 209mm  
LB: 259mm  
NGBe96 L — B: 206mm  
L: 236mm  
LB: 286mm

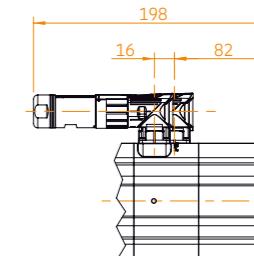
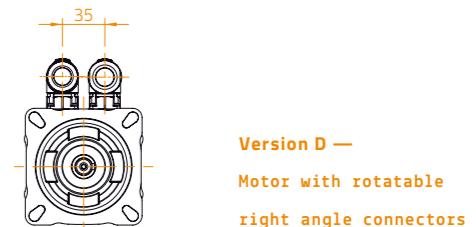
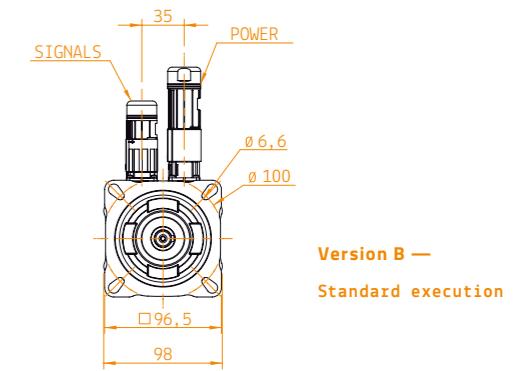
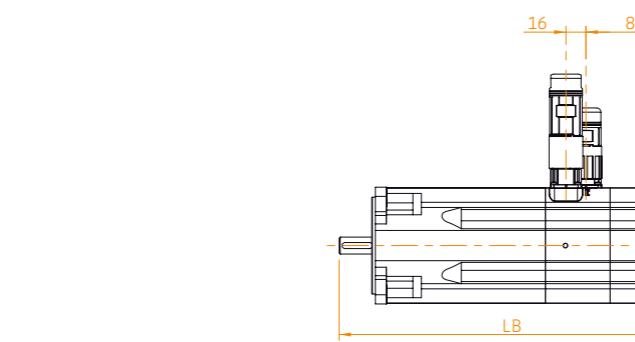
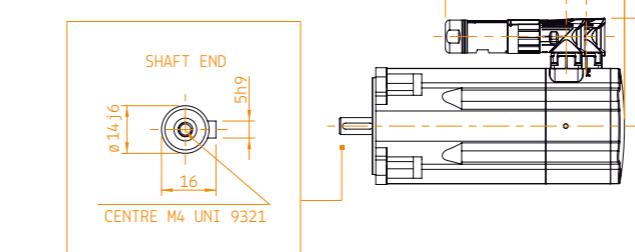
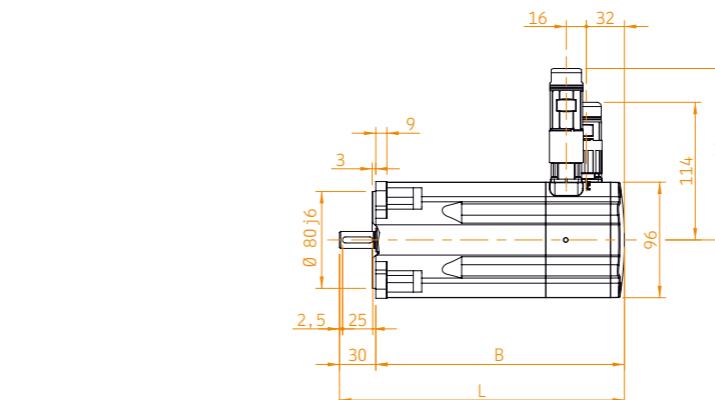


Torque constant —  
The torque  
is proportional  
to the motor current

$$K_t = \frac{M_n}{I_n}$$

Others informations:  
more data are available  
on technical manual of  
NGBe motor

Max torque  
S3 - 40% 1'  
S1 torque



Version D —  
Motor with rotatable  
right angle connectors

Motor with brake —  
Left: Version B  
Right: Version D

## NGBe123 TENV - 8 poles - 3x360VRMS motor power supply

code	Nominal speed Nn	Duty cycle S1			Duty cycle S3-40%, 1 min			Peak torque M <sub>peak</sub>	Torque constant K <sub>t</sub>	Inertia J	Weight m
		Stall torque M <sub>n0</sub>	Nominal torque M <sub>n</sub>	Stall current I <sub>n0</sub>	Stall torque M <sub>n0</sub> [S3]	Nominal torque M <sub>n</sub> [S3]					
NGBe123S	AK	3000 Rpm	7.2 Nm	5.7 Nm	5.3 A <sub>RMS</sub>	10.9 Nm	8.8 Nm	18 Nm	1.36 Nm/A <sub>RMS</sub>	8.2 kgcm <sup>2</sup>	6.7 kg
NGBe123M	AJ	3000 Rpm	9.6 Nm	7.2 Nm	6.5 A <sub>RMS</sub>	14.8 Nm	11.3 Nm	25 Nm	1.48 Nm/A <sub>RMS</sub>	12.1 kgcm <sup>2</sup>	8.7 kg
NGBe123L	AG	3000 Rpm	11.9 Nm	8.5 Nm	8 A <sub>RMS</sub>	18.4 Nm	13.4 Nm	36 Nm	1.49 Nm/A <sub>RMS</sub>	16.1 kgcm <sup>2</sup>	10.7 kg
NGBe123S	AI	5000 Rpm	7.2 Nm	4.5 Nm	8.7 A <sub>RMS</sub>	10.9 Nm	7.0 Nm	18 Nm	0.83 Nm/A <sub>RMS</sub>	8.2 kgcm <sup>2</sup>	6.7 kg
NGBe123M	AF	5000 Rpm	9.6 Nm	4.9 Nm	10.5 A <sub>RMS</sub>	14.8 Nm	7.8 Nm	25 Nm	0.91 Nm/A <sub>RMS</sub>	12.1 kgcm <sup>2</sup>	8.7 kg
NGBe123L	AD	5000 Rpm	11.9 Nm	4.5 Nm	13.2 A <sub>RMS</sub>	18.4 Nm	7.3 Nm	36 Nm	0.90 Nm/A <sub>RMS</sub>	16.1 kgcm <sup>2</sup>	10.7 kg



NGBe123S — B: 183mm

L: 233mm

LB: 287mm

NGBe123M — B: 210mm

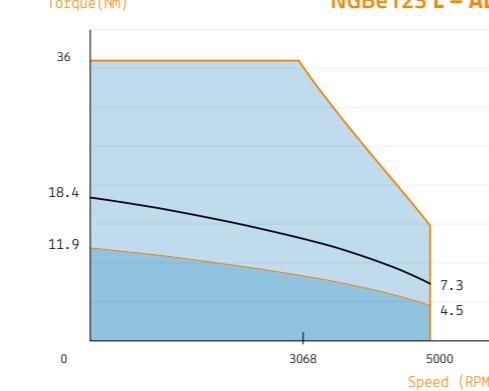
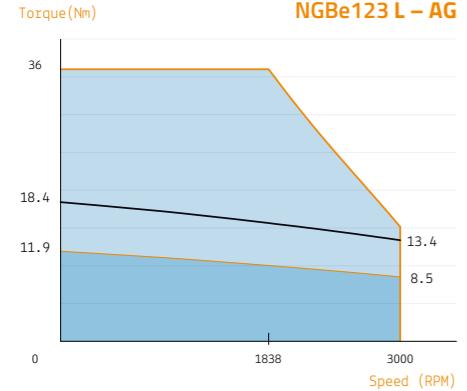
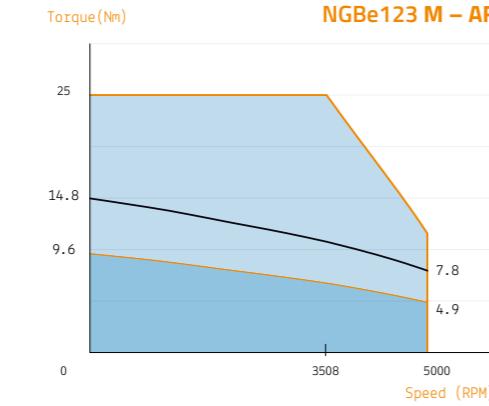
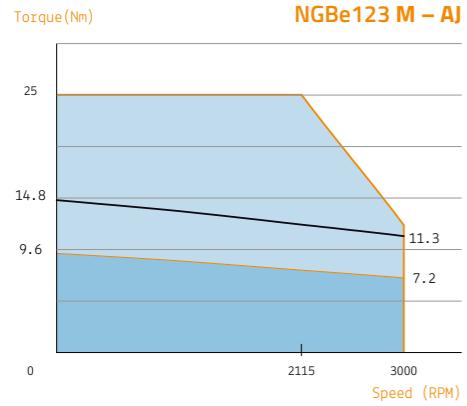
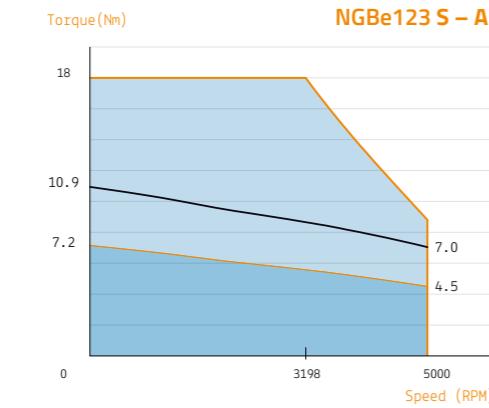
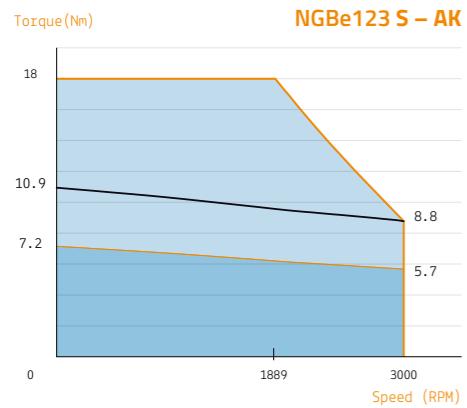
L: 260mm

LB: 314mm

NGBe123L — B: 236mm

L: 286mm

LB: 340mm

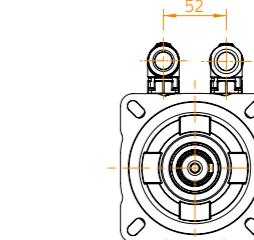
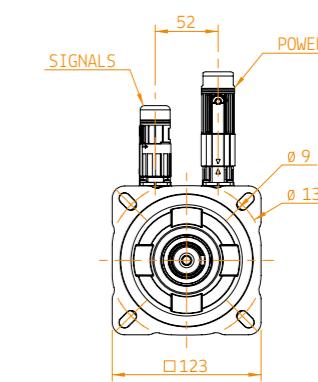
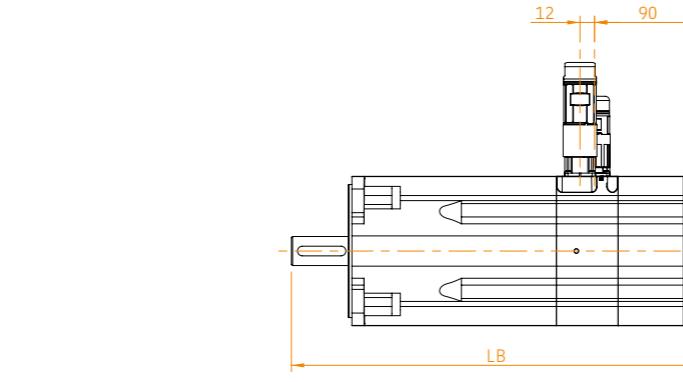
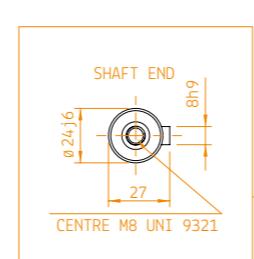
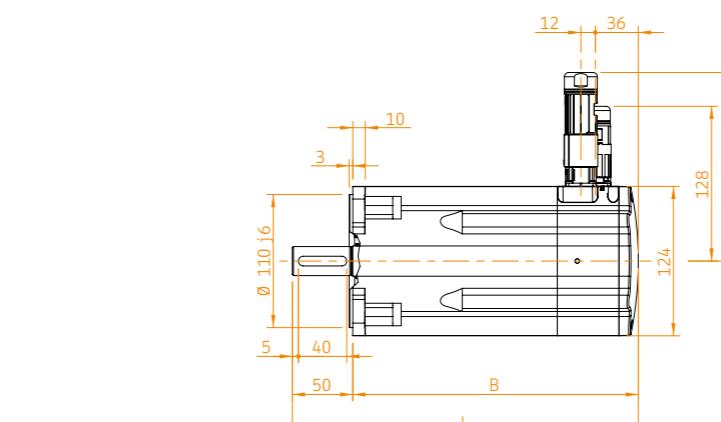


**Torque constant —**  
The torque  
is proportional  
to the motor current

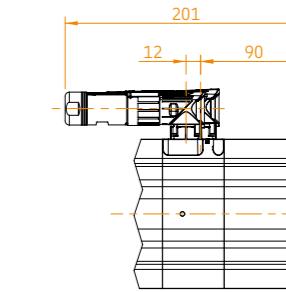
$$K_t = \frac{M_n}{I_n}$$

**Others informations:**  
more data are available  
on technical manual of  
NGBe motor

**Max torque**  
S3 - 40% 1'  
**S1 torque**



**Version D —**  
Motor with rotatable  
right angle connectors



**Motor with brake —**  
Left: Version B  
Right: Version D

## NGBe143 TENV - 8 poles - 3x360VRMS motor power supply

code	Nominal speed Nn	Duty cycle S1			Duty cycle S3-40%, 1 min			Peak torque M <sub>peak</sub>	Torque constant K <sub>t</sub>	Inertia J	Weight
		Stall torque M <sub>n0</sub>	Nominal torque M <sub>n</sub>	Stall current I <sub>n0</sub>	Stall torque M <sub>n0</sub> [S3]	Nominal torque M <sub>n</sub> [S3]					
NGBe143S	BD	3000 Rpm	12.5 Nm	9.5 Nm	9.4 A <sub>RMS</sub>	19.7 Nm	15.1 Nm	36.9 Nm	1.33 Nm/A <sub>RMS</sub>	28 kgcm <sup>2</sup>	8.8 kg
NGBe143M	BC	3000 Rpm	18.8 Nm	11.5 Nm	13.9 A <sub>RMS</sub>	29.5 Nm	18.3 Nm	56.3 Nm	1.35 Nm/A <sub>RMS</sub>	38 kgcm <sup>2</sup>	12 kg
NGBe143L	AE	3000 Rpm	25 Nm	12.7 Nm	16.6 A <sub>RMS</sub>	39.4 Nm	20.2 Nm	75 Nm	1.51 Nm/A <sub>RMS</sub>	49 kgcm <sup>2</sup>	15.1 kg
NGBe143P	AD	3000 Rpm	30 Nm	13.1 Nm	19.8 A <sub>RMS</sub>	47.3 Nm	20.8 Nm	90 Nm	1.52 Nm/A <sub>RMS</sub>	60 kgcm <sup>2</sup>	18.2 kg

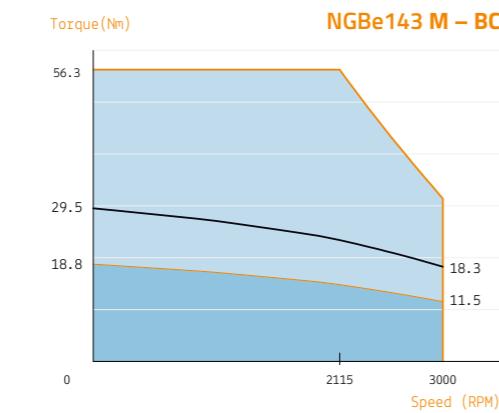
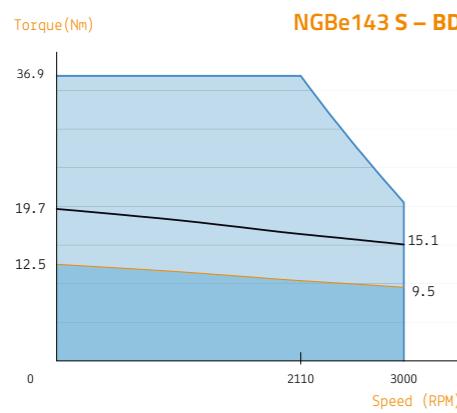


NGBe143S — B: 221mm  
L: 279mm  
LB: 344mm

NGBe143M — B: 258mm  
L: 316mm  
LB: 381mm

NGBe143L — B: 295mm  
L: 353mm  
LB: 418mm

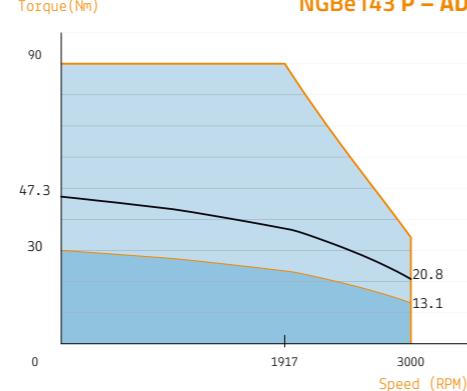
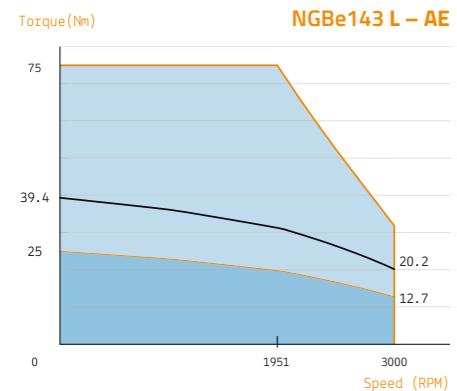
NGBe143P — B: 332mm  
L: 390mm  
LB: 455mm



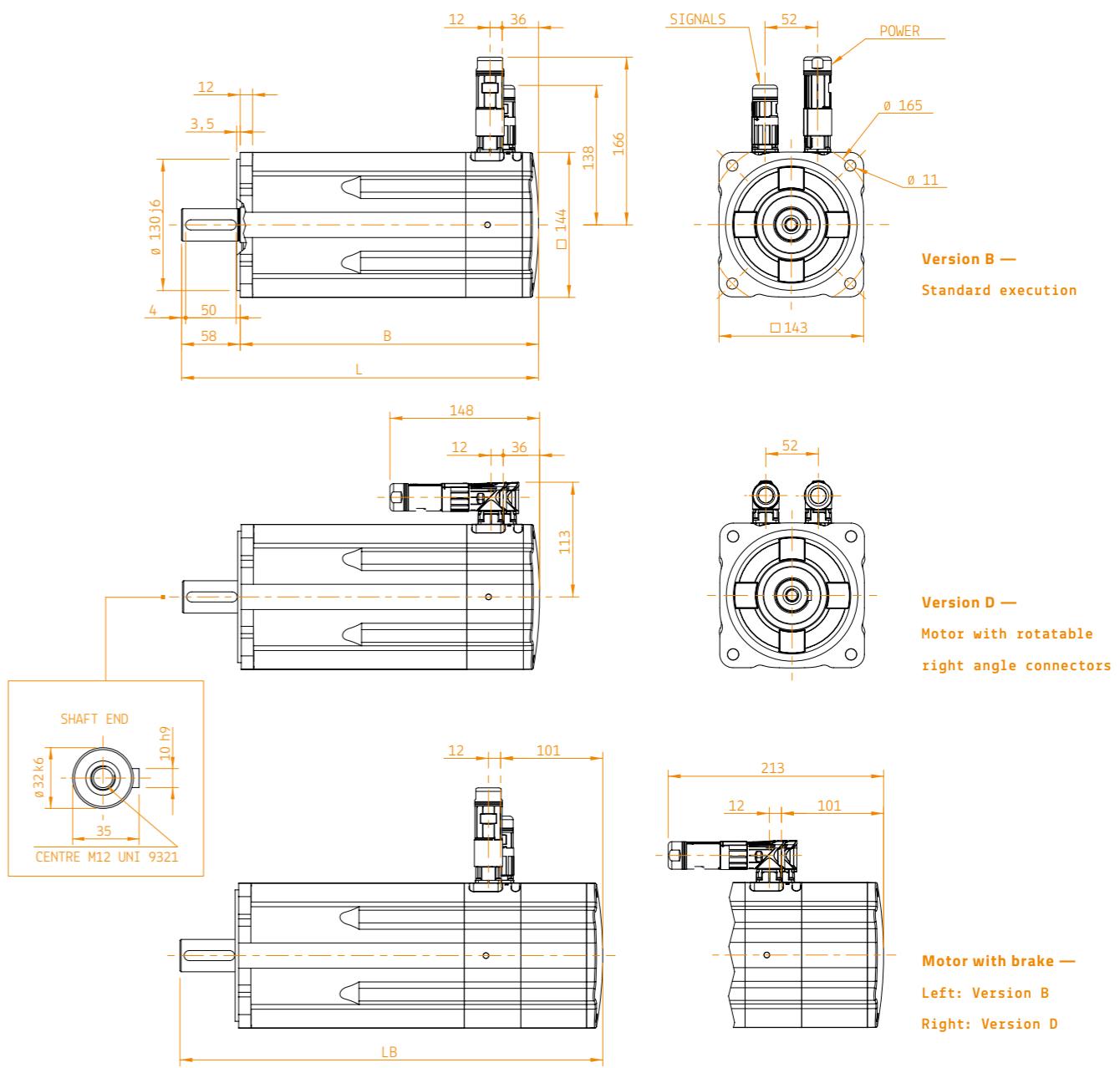
**Torque constant —**  
The torque  
is proportional  
to the motor current

$$K_t = \frac{M_n}{I_n}$$

Others informations:  
more data are available  
on technical manual of  
NGBe motor



**Max torque** —  
S3 - 40% 1'  
**S1 torque** —



## NGBe143 TEBC - 8 poles - 3x360VRMS motor power supply

code	Nominal speed Nn	Duty cycle S1			Duty cycle S3-40%, 1 min			Peak torque M <sub>peak</sub>	Torque costant K <sub>t</sub>	Inertia J	Weight m
		Stall torque M <sub>n0</sub>	Nominal torque M <sub>n</sub>	Stall current I <sub>n0</sub>	Stall torque M <sub>n0</sub> [S3]	Nominal torque M <sub>n</sub> [S3]					
NGBe143S	BD	3000 Rpm	17.3 Nm	14.7 Nm	13 A <sub>RMS</sub>	26.9 Nm	23.1 Nm	36.9 Nm	1.33 Nm/A <sub>RMS</sub>	28 kgcm <sup>2</sup>	11.8 kg
NGBe143M	BC	3000 Rpm	24.7 Nm	19.9 Nm	18.3 A <sub>RMS</sub>	38.5 Nm	31.3 Nm	56.3 Nm	1.35 Nm/A <sub>RMS</sub>	38 kgcm <sup>2</sup>	15.3 kg
NGBe143L	AE	3000 Rpm	31.8 Nm	24.6 Nm	21.3 A <sub>RMS</sub>	49.7 Nm	39.8 Nm	75 Nm	1.49 Nm/A <sub>RMS</sub>	49 kgcm <sup>2</sup>	18.7 kg
NGBe143P	AD*	3000 Rpm	38.7 Nm	29 Nm	25.5 A <sub>RMS</sub>	60.5 Nm	46.3 Nm	90 Nm	1.52 Nm/A <sub>RMS</sub>	60 kgcm <sup>2</sup>	22.1 kg

\*Scatola morsetti disponibile per NGBe143 e obbligatoria per NGBe143P

\*Motor with terminal box is available for NGBe143 and mandatory for NGBe143P only

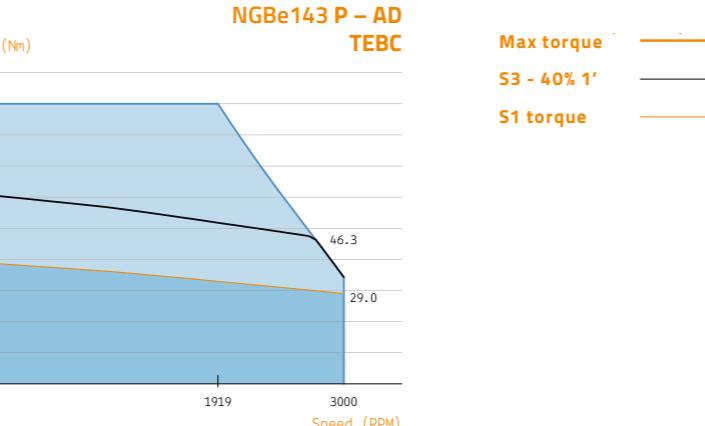
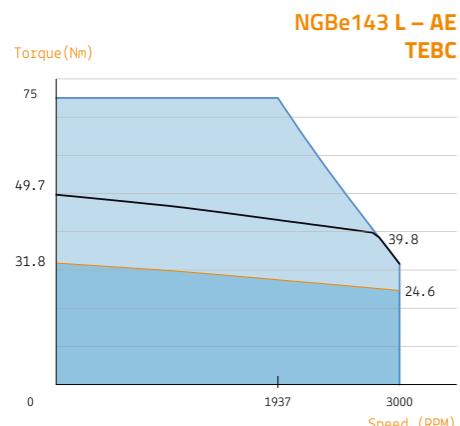
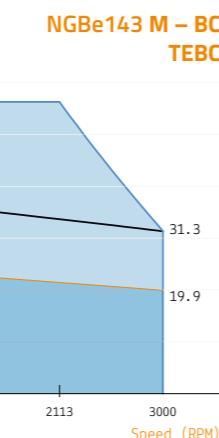
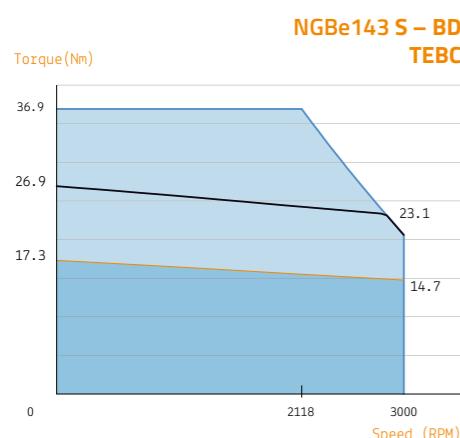


NGBe143S — B: 332mm  
L: 390mm  
LB: 577mm  
NGBe143M — B: 369mm  
L: 427mm  
LB: 566mm  
NGBe143L — B: 406mm  
L: 464mm  
LB: 529mm  
NGBe143P — B: 443mm  
L: 501mm  
LB: 492mm

## Totally Enclosed Blower Cooled

La versione ventilata del NGBe consente di raggiungere coppie continuative più elevate in tutto il range di velocità. Si presta ad applicazioni dove il ciclo macchina è particolarmente oneroso. Prevede elettroventilatore con alimentazione 1x230Vac, 50/60Hz, 0.25A, 42W con connettore industriale M16 3 pin.

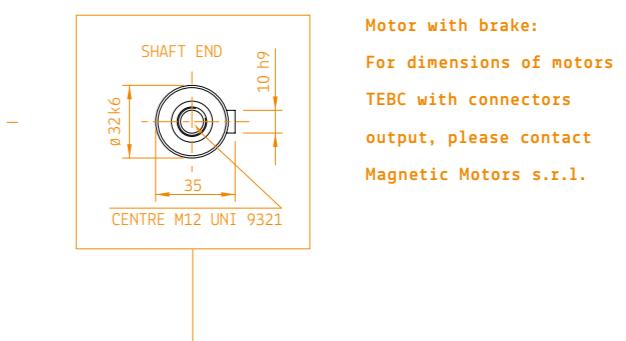
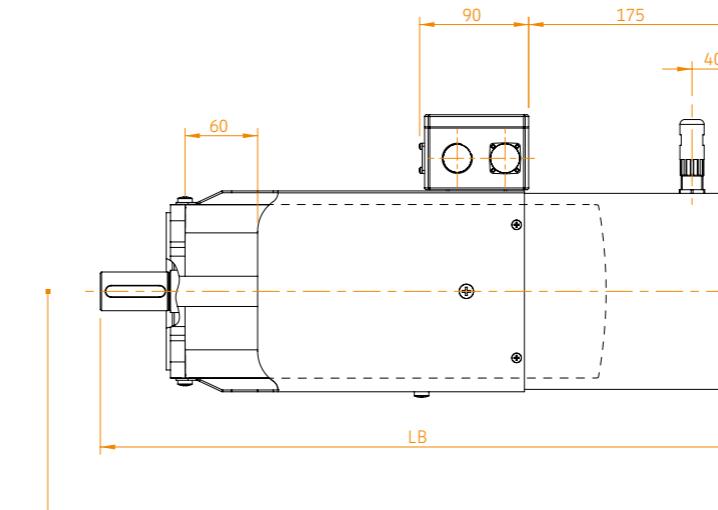
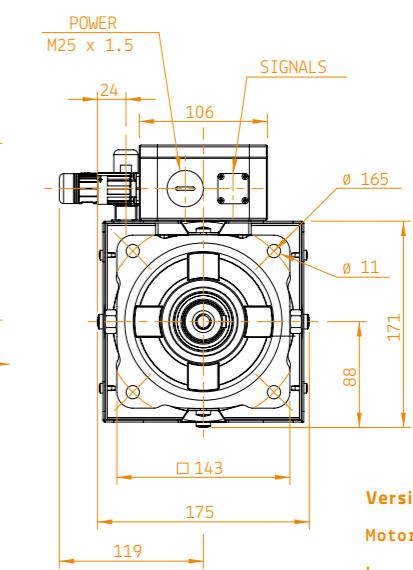
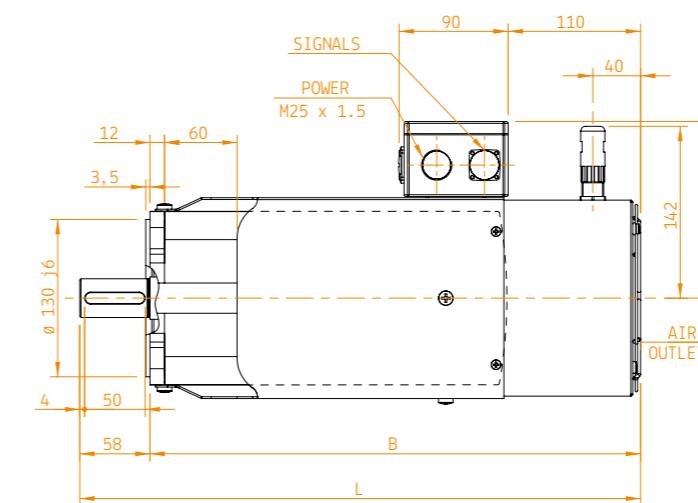
The NGBe143 TEBC reaches higher continuous torque over the whole speed range. It is suitable for applications where machine cycle is particularly heavy. Fan supply 1x230Vac, 50/60Hz, 0.25A, 42W with M16 3 pins connector.



**Torque costant —**  
The torque is proportional to the motor current

$$K_t = \frac{M_n}{I_n}$$

**Others informations:**  
more data are available on technical manual of NGBe motor



## NGBe200 TENV - 8 poles - 3x360VRMS motor power supply

code	Nominal speed Nn	Duty cycle S1			Duty cycle S3-40% 1 min			Peak torque M <sub>peak</sub>	Torque costant K <sub>t</sub>	Inertia J	Weight m
		Stall torque Mn <sub>0</sub>	Nominal torque Mn	Stall current In <sub>0</sub>	Stall torque Mn <sub>0</sub> [S3]	Nominal torque Mn [S3]					
NGBe200S	AJ	3000 Rpm	42 Nm	24,5 A <sub>RMS</sub>	28,1 A <sub>RMS</sub>	65,9 Nm	38,8 Nm	126 Nm	1,50 Nm/A <sub>RMS</sub>	66 kgcm <sup>2</sup>	29 kg
NGBe200M	AF	3000 Rpm	57 Nm	19,8 Nm	38,8 A <sub>RMS</sub>	89,9 Nm	31,4 Nm	171 Nm	1,47 Nm/A <sub>RMS</sub>	94 kgcm <sup>2</sup>	43 kg
NGBe200L	AK	2000 Rpm	68 Nm	34,4 Nm	28,2 A <sub>RMS</sub>	107,5 Nm	54,4 Nm	204 Nm	2,41 Nm/A <sub>RMS</sub>	122 kgcm <sup>2</sup>	48 kg
NGBe200P	AF	2000 Rpm	75 Nm	27,2 Nm	31,4 A <sub>RMS</sub>	118,7 Nm	42,9 Nm	225 Nm	2,39 Nm/A <sub>RMS</sub>	150 kgcm <sup>2</sup>	60 kg

\*Motor with connectors output is available for NGBe200

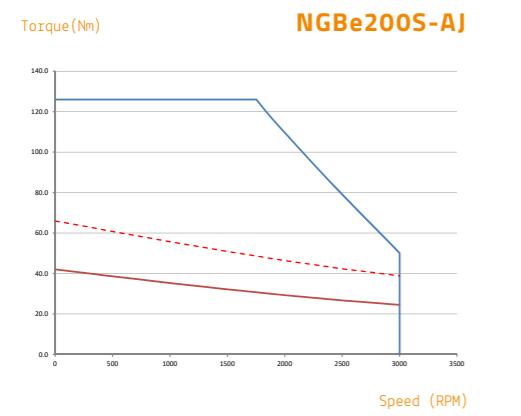


NGBe200 S - B: 322mm  
L: 404mm

NGBe200 M - B: 376mm  
L: 458mm

NGBe200 L - B: 430mm  
L: 512mm

NGBe200 P - B: 484mm  
L: 566mm



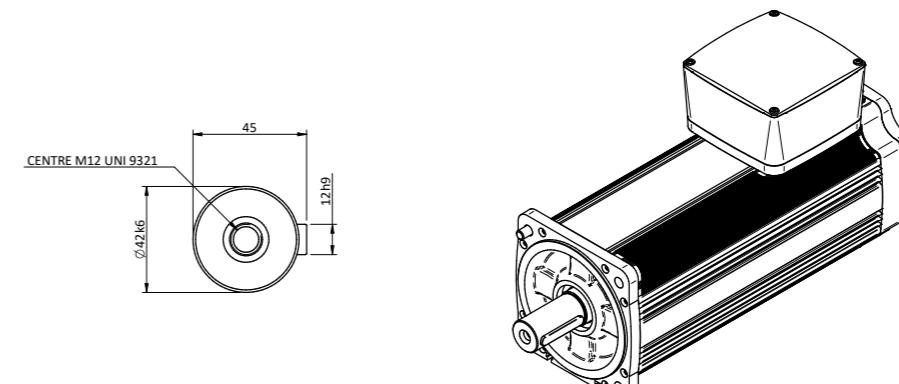
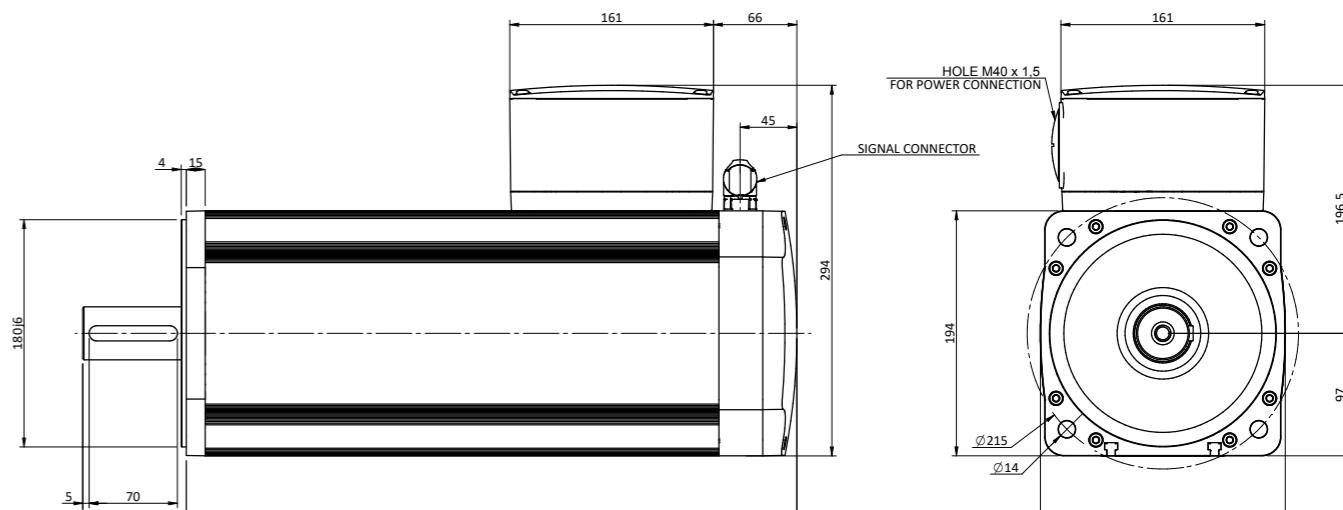
**Torque costant —**  
The torque is proportional to the motor current

$$M_n = \frac{K_t}{I_n}$$

**Others informations:**  
more data are available on technical manual of NGBe motor



**Max torque .**  
**S3 - 40% 1'**  
**S1 torque**



## NGBe200 TEBC - 8 poles - 3x360VRMS motor power supply

code	Nominal speed Nn	Duty cycle S1			Duty cycle S3-40% 1 min			Peak torque M <sub>peak</sub>	Torque costant K <sub>t</sub>	Inertia J	Weight kg
		Stall torque Mn <sub>0</sub>	Nominal torque Mn	Stall current I <sub>n0</sub>	Stall torque Mn <sub>0</sub> [S3]	Nominal torque Mn [S3]					
NGBe200S	AH	3000 Rpm	58 Nm	46,9 Nm	49,3 A <sub>RMS</sub>	88,8 Nm	69,8 Nm	126 Nm	1,18 Nm/A <sub>RMS</sub>	66 kgcm <sup>2</sup>	32 kg
NGBe200M	AF	3000 Rpm	84 Nm	65,8 Nm	60,2 A <sub>RMS</sub>	129,4 Nm	91,6 Nm	171 Nm	1,39 Nm/A <sub>RMS</sub>	94 kgcm <sup>2</sup>	46 kg
NGBe200L	AD	3000 Rpm	108 Nm	81,9 Nm	70,3 A <sub>RMS</sub>	166,7 Nm	119,6 Nm	204 Nm	1,49 Nm/A <sub>RMS</sub>	122 kgcm <sup>2</sup>	51 kg
NGBe200P	AC	3000 Rpm	128 Nm	99,2 Nm	76,7 A <sub>RMS</sub>	199,5 Nm	121,9 Nm	225 Nm	1,67 Nm/A <sub>RMS</sub>	150 kgcm <sup>2</sup>	64 kg

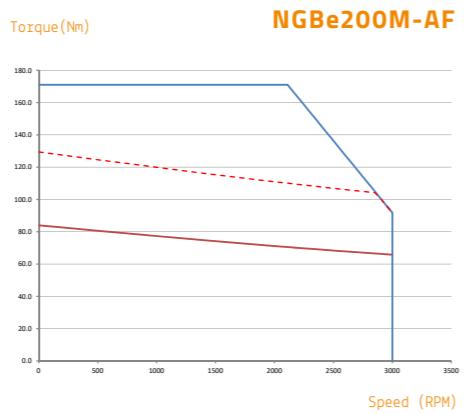
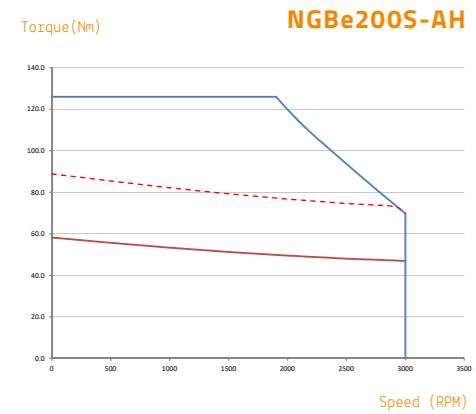


**NGBe200 S** - B: 428mm  
 L: 510mm  
**NGBe200 M** - B: 482mm  
 L: 564mm  
**NGBe200 L** - B: 536mm  
 L: 618mm  
**NGBe200 P** - B: 590mm  
 L: 672mm

## Totally Enclosed Blower Cooled

Prevede elettroventilatore con alimentazione 3x400Vac, 50/60Hz, 0,17/0,13A, 68/70W connected on M23 6 pins connector.

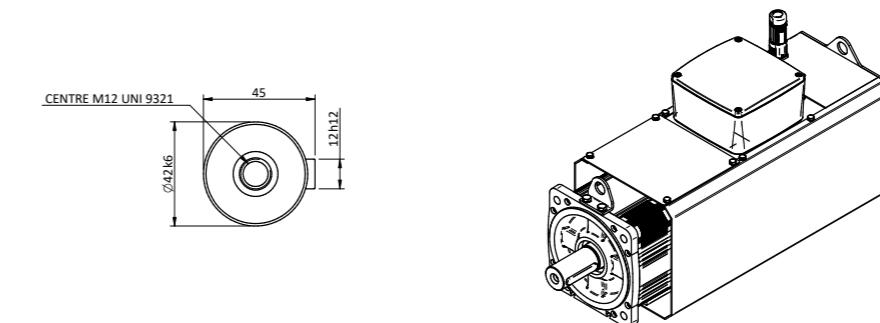
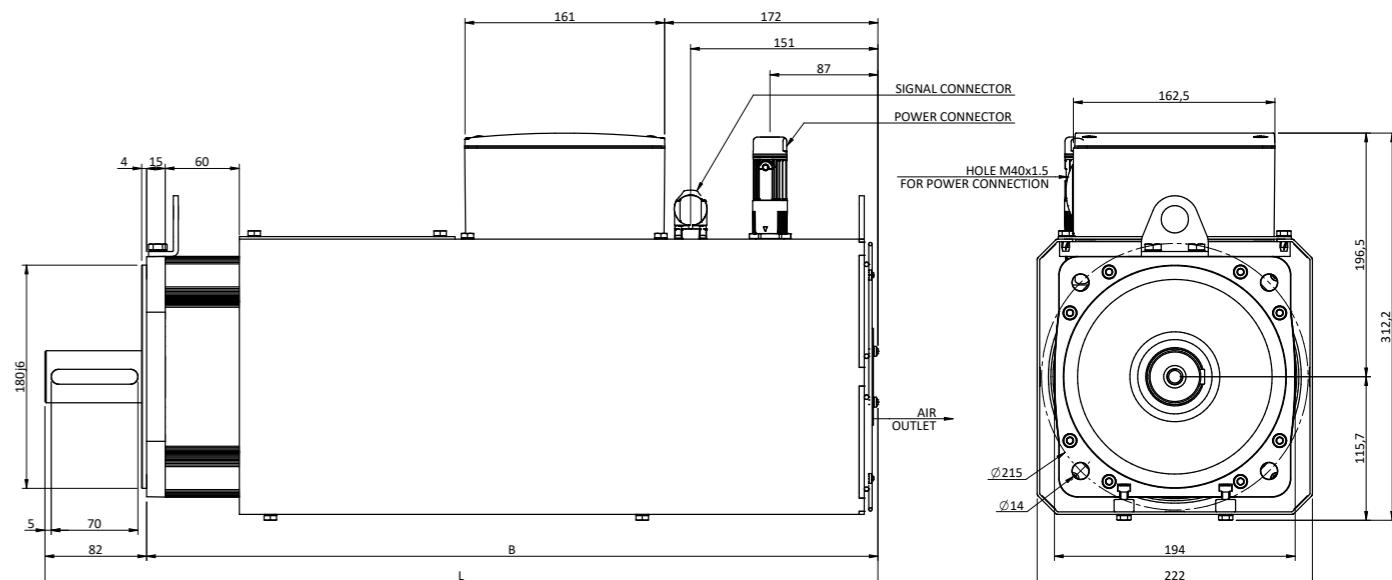
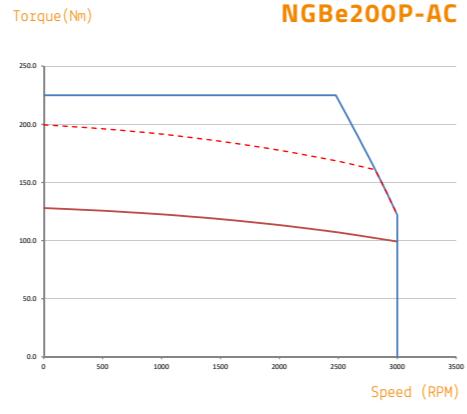
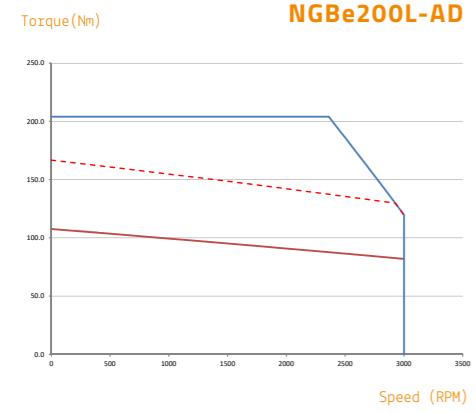
Fan supply 3x400Vac, 50/60Hz, 0,17/0,13A,  
68/70W connected on M23 6 pins connector.



**Torque costant —**  
The torque  
is proportional  
to the motor current

$$K_t = \frac{M_n}{I_n}$$

**Others informations:**  
more data are available  
on technical manual of  
NGBe motor



## NGBe260 TENV - 8 poles - 3x360VRMS motor power supply

\*preliminary data

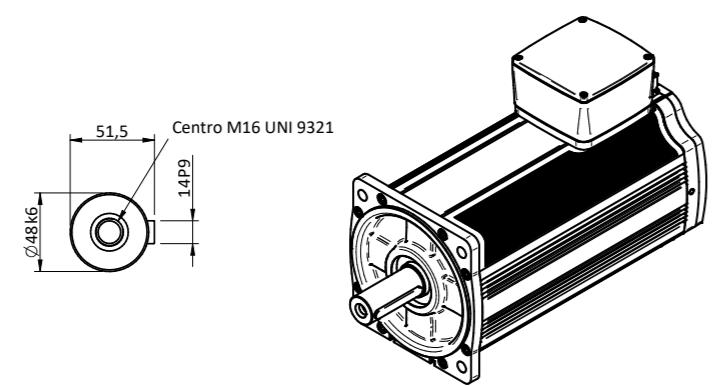
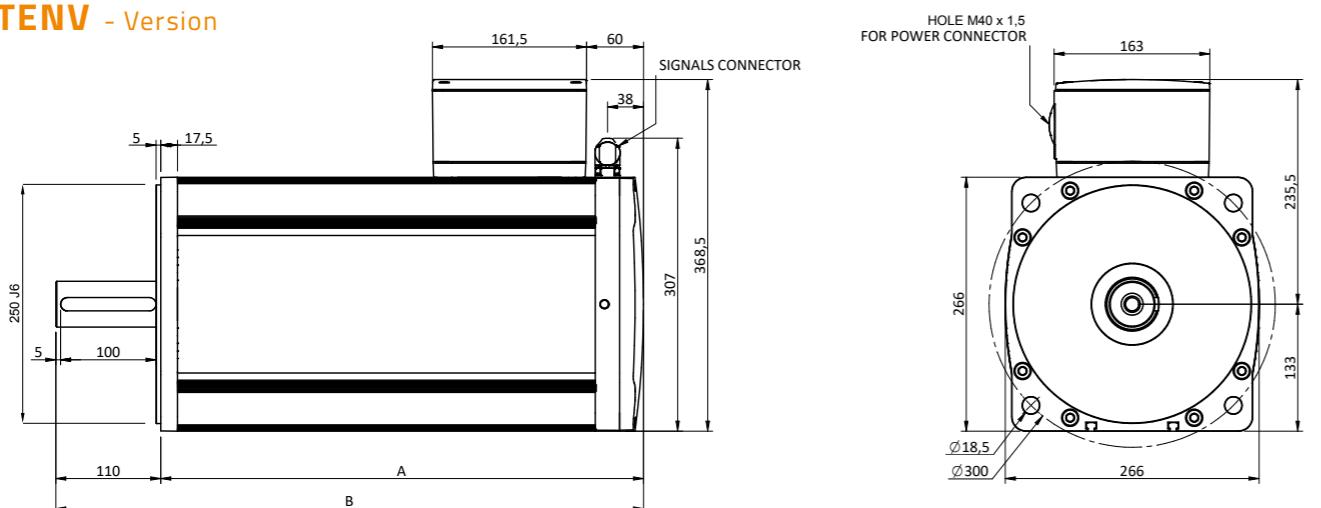
	code	Nominal speed Nn	Stall torque $M_{n_0}$	Nominal torque Mn	Stall current $I_{n_0}$	Peak torque Nm	Torque constante Nm/A	Inertia Kgcm <sup>2</sup>	Weight kg
NGBe260S	S1	2000 Rpm	120 Nm	68 Nm	54 A <sub>RES</sub>	370 Nm	2,2 Nm/A <sub>RES</sub>	284 kgcm <sup>2</sup>	75 kg
NGBe260M	S2	2000 Rpm	175 Nm	67 Nm	79 A <sub>RES</sub>	550 Nm	2,2 Nm/A <sub>RES</sub>	427 kgcm <sup>2</sup>	96 kg
NGBe260L	S3	2000 Rpm	230 Nm	32 Nm	102 A <sub>RES</sub>	740 Nm	2,3 Nm/A <sub>RES</sub>	569 kgcm <sup>2</sup>	120 kg
NGBe260P	S4	2000 Rpm	280 Nm	20 Nm	121 A <sub>RES</sub>	920 Nm	2,3 Nm/A <sub>RES</sub>	711 kgcm <sup>2</sup>	142 kg

## NGBe260 TEBC - 8 poles - 3x360VRMS motor power supply

\*preliminary data

	code	Nominal speed Nn	Stall torque $M_{n_0}$	Nominal torque Mn	Stall current $I_{n_0}$	Peak torque Nm	Torque constante Nm/A	Inertia Kgcm <sup>2</sup>	Weight kg
NGBe260S	S1	3000 Rpm	190 Nm	135 Nm	147 A <sub>RES</sub>	370 Nm	1,29 Nm/A <sub>RES</sub>	284 kgcm <sup>2</sup>	87 kg
NGBe260M	S2	3000 Rpm	280 Nm	170 Nm	200 A <sub>RES</sub>	550 Nm	1,40 Nm/A <sub>RES</sub>	427 kgcm <sup>2</sup>	109 kg
NGBe260L	S3	3000 Rpm	360 Nm	190 Nm	245 A <sub>RES</sub>	740 Nm	1,47 Nm/A <sub>RES</sub>	569 kgcm <sup>2</sup>	133 kg
NGBe260P	S4	3000 Rpm	440 Nm	200 Nm	275 A <sub>RES</sub>	920 Nm	1,60 Nm/A <sub>RES</sub>	711 kgcm <sup>2</sup>	156 kg

## TENV - Version



NGBe260 S - A: 422mm  
B: 532mm  
NGBe260 M - A: 506mm  
B: 616mm  
NGBe260 L - A: 590mm  
B: 700mm  
NGBe260 P - A: 674mm  
B: 784mm



**ACCESSORI**  
**ACCESSORIES**

## Connessioni motore - Motor connection

### Sistema di feedback del motore - Motor feedback system

Il motore è fornito completo di resolver o di encoder, alloggiato nello scudo posteriore per la protezione contro gli urti accidentali. Sono disponibili i seguenti tipi:

- **Resolver 2 poles:** Sine-Cosine wave – 2 poles – 0.5 ratio transformation
- **Encoder TTL + Hall S., Abs. singleturn:** incremental signal TTL2048 ppr (max 150 kHz) – 5 Vdc Line driver – Commutation signals – Zero pulse
- **Encoder Sin Cos Abs. singleturn:** incremental signal sinusoidale 2048 ppr – 1 Vpp signal SinCos + zero pulse – 1 period absolute waves/rev. – 5Vdc
- **Encoder BiSS Abs. multiturn:** absolute multiturn BiSS interface – incremental sinusoidal signal 2048 ppr – 19 bit singleturn + 12 multiturn – 5Vdc

Altri encoder (Endat, Hyperface ..) o sole predisposizioni sono possibili su richiesta.

### Freno — Brake

Su richiesta è disponibile il motore completo di freno di stazionamento che si inserisce in mancanza di alimentazione (freno negativo). Tale freno è previsto per mantenere bloccato l'asse e deve essere inserito a velocità prossima a zero: le operazioni di frenatura del motore in velocità sono infatti delle frenature elettriche effettuate tramite l'inverter e non svolte o assistite dal freno. L'alimentazione a 24 Vdc è cablata sul connettore di potenza.

*The motor is provided with a resolver or encoder housed in the rear shield to protect it against accidental impacts. The following types are available:*

- **2-pole resolver:** Sine-Cosine wave – 2 poles – 0.5 transformation ratio
- **Encoder TTL + Hall S., Abs. singleturn:** incremental signal TTL2048 ppr (max 150 kHz) – 5 Vdc Line driver – Commutation signals – Zero pulse
- **Encoder Sin Cos Abs. single turn:** incremental signal sinusoidale 2048 ppr – 1 Vpp signal SinCos + zero pulse – 1 period absolute waves/rev. – 5Vdc
- **Encoder BiSS Abs. multi-turn:** absolute multiturn BiSS interface – incremental sinusoidal signal 2048 ppr – 19 bit singleturn + 12 multiturn – 5Vdc

*Other encoders (Endat, Hyperface, etc.) or other set-ups are available upon request.*

### Protezione termica — Power connection

I servomotori possono essere forniti con uno dei seguenti tipi di sensore termico:  
**Termoresistenza tipo KTY 84-130**  
**Termocontatto N.C. klixon**

*The servo motors can be supplied with one of the following types of thermal sensor:  
**Resistance thermometer type KTY 84-130**  
**Temperature Switch N.C. klixon***

### Verniciatura — Painting

I motori vengono forniti verniciati in RAL9005 o RAL5002, con vernici a polvere che assicurano elevate caratteristiche meccaniche (durezza, elasticità) e una buona finitura delle superfici del motore. A richiesta possiamo realizzare una verniciatura smalto monocolor su specifiche a richiesta del cliente.

*The motors are painted with two colours, RAL9005 or RAL5002, with powder paints that ensure high mechanical features (hardness, elasticity) and a good finish of the motor's surfaces. Single-colour enamel paint available upon request.*

### Anello paraolio — Seal ring

Tutti i motori possono essere equipaggiati con anello di tenuta paraolio con molla per applicazioni dove è previsto il bagno d'olio, mentre su richiesta è possibile fornire anche la versione solo per tenuta IP65 sull'albero.

*All motors can be equipped with oil seal ring with a spring for applications requiring oil bath. The specific version for an IP65 seal on the shaft can be supplied upon request.*

### Inerzia supplementare — Ring seal

Su richiesta è possibile prevedere un'inerzia aggiuntiva per migliorare il controllo del motore (opzione disponibile solo nella versione senza freno).

*Extra inertia can be added upon request to improve motor control (option available only in the brakeless version).*

	Additional inertia $\Delta J$	Additional weight $\Delta m$
<b>NGBe96</b>	+ 1.1 kgcm <sup>2</sup>	+ 0.4 kg
<b>NGBe123</b>	+ 7.5 kgcm <sup>2</sup>	+ 1.0 kg
<b>NGBe143</b>	+ 22.8 kgcm <sup>2</sup>	+ 1.9 kg

	Nominal torque @20°C M <sub>n</sub>	Stall torque @100°C M <sub>stat</sub>	Inertia $* \Delta J$	Weight $* \Delta m$
<b>NGBe96</b>	4.5 Nm	4.0 Nm	0.12 kgcm <sup>2</sup>	0.3 kg
<b>NGBe123</b>	18 Nm	15 Nm	1.66 kgcm <sup>2</sup>	0.9 kg
<b>NGBe143</b>	36 Nm	32 Nm	5.56 kgcm <sup>2</sup>	1.6 kg

\* Aggiuntiva a quella del motore – To be added to the motor torque

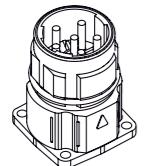
(Versione NGBe200 e NGBe260 con freno: Disponibile a breve – NGBe200 and NGBe260 with brake: coming soon)

## Connessioni motore — Motor connection

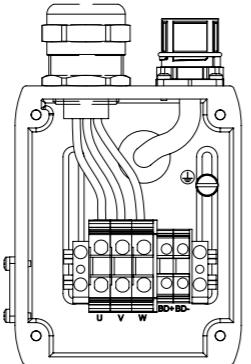
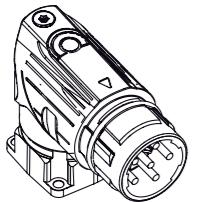
### Connessioni di potenza 6 pins — Power connection 6 pins

Connessione di potenza  
+ connessione freno di stazionamento.

*Power connections  
+ parking brake connection.*



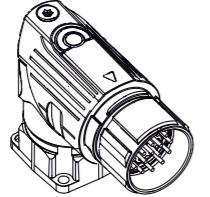
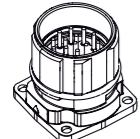
**connector M23 —**  
Straight or adjustable  
to 90 °, fitted for  
both quick-coupling for  
in thread engagement.  
Connector M40 for  
NGBe200 available  
upon request.



**Terminal adjustable box**  
**2 positions —**  
Available for NGBe143,  
NGBe200 and NGBe260

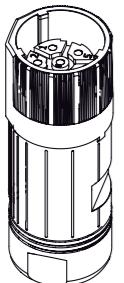
### Connessioni di segnale 17 pins — Signal connection 17 pins

Connessione trasduttore velocità/posizione. *Speed/position transducer connection.*

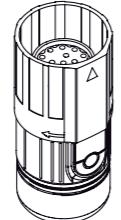


**connector M23 —**  
Straight or adjustable  
to 90 °, fitted for  
both quick-coupling for  
in thread engagement.

### Connettori volanti opzionali — Optional mobile connectors



**Free connector M23 —**  
6 pins power connector,  
quick coupling.



**Free connector M23 —**  
17 pins signal connector,  
quick coupling.

### Cavi opzionali — Optional cables

A richiesta possiamo fornire cavi  
di alimentazione e di controllo servomotore  
della lunghezza desiderata completi  
di connettore ad innesto rapido lato motore.

*Servomotor control and power cables  
(of the required length) complete  
with quick coupling connector on the  
motor side can be supplied upon request.*



ORANGE1  
HOLDING

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